



Generating Speakers by Prompting Listener Impressions for Pre-trained Multi-Speaker Text-to-Speech Systems

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Abstract

This paper proposes a speech synthesis system that allows users to specify and control the acoustic characteristics of a speaker by means of prompts describing the speaker's traits of synthesized speech. Unlike previous approaches, our method utilizes listener impressions to construct prompts, which are easier to collect and align more naturally with everyday descriptions of speaker traits. We adopt the Low-rank Adaptation (LoRA) technique to swiftly tailor a pre-trained language model to our needs, facilitating the extraction of speaker-related traits from the prompt text. Besides, different from other prompt-driven text-to-speech (TTS) systems, we separate the prompt-to-speaker module from the multi-speaker TTS system, enhancing system flexibility and compatibility with various pre-trained multi-speaker TTS systems. Moreover, for the prompt-to-speaker characteristic module, we also compared the discriminative method and flow-matching based generative method and we found that combining both methods can help the system simultaneously capture speaker-related information from prompts better and generate speech with higher fidelity.

Index Terms: multi-speaker text-to-speech, prompt, listener impression

1. Introduction

Multi-speaker text-to-speech systems [1, 2, 3] aim to synthesize natural speech conditioned on the specific content text and target speaker information. The speaker information can be provided by speaker ID, reference speech, or encoded speaker embedding. However, the available speaker ID must be used in the training process and the reference speech could be hard to find in a short period if we want to create some unseen voices. Besides, providing reference speech may not be user-friendly for some ordinary users.

Natural language serves as the most intuitive and comprehensive medium for humans to communicate information. Recent research endeavors have aimed at harnessing this capability within text-to-speech (TTS) systems by controlling speaker-related attributes through textual descriptions, commonly referred to as prompts. Studies such as those by Guo et al. [4], Leng et al. [5], Liu et al. [6], and Yang et al. [7] mainly explore the manipulation of style-related attributes via text prompts. Conversely, Zhang et al. [8] investigated the modulation of speaker identity information. Extending this domain, Shimizu et al. [9] used prompts to concurrently modulate both style and speaker identity attributes.

Despite notable advancements in prompt-driven text-to-speech (TTS) technology, several persistent challenges merit further investigation. The authors in [4, 5] have trained their systems using datasets with paired speech and prompt descrip-

tions. However, acquiring TTS training data is much easier than procuring prompt-specific data [7, 8]. This discrepancy suggests that decoupling the TTS model from the prompt-modulation model may be advantageous. Typically, the pre-trained language models (LM) used for encoding prompt information are developed using general-purpose datasets. As such, it may not suffice to merely integrate basic modules [7, 8] atop these LMs to tailor them for TTS applications. Meanwhile, the methods for collecting prompt data can be categorized into two main approaches: deriving statistical signal processing measures [4, 5], such as pitch and speed, from larger datasets automatically; or directly collecting small-scale prompts manually [7, 8], which involves a more curated and thus potentially less scalable process. Identifying more effective strategies for gathering prompt data remains a crucial area for exploration.

We propose generating the prompts from listener impression scores, which can be more easily collected than the complete prompt descriptions and align more closely with natural descriptions of voice in daily conversations compared with the signal processing statistics-based prompts. Furthermore, we address the challenge of pre-trained LMs, which are typically trained on general datasets that may not effectively capture nuances related to speaker identity and speaking styles. To this end, we use a low-rank adaptation strategy (LoRA) [10], adapting the pre-trained LM to better suit our specific requirements. Our experimental results underscore the significance of the LoRA module in enhancing overall performance. Additionally, different from the previous works [4, 5], we propose a modular design for the prompt-based TTS system, decoupling the prompt-to-speaker module from the TTS system. This separation increases the system's flexibility, allowing for seamless integration with various multi-speaker TTS frameworks. When mapping the prompt to another modality, researchers have used either a discriminative method [6, 7, 11, 12, 13] or generative method [8]. Our findings indicate that each method offers distinct benefits, and a hybrid approach that combines both methods yields further enhancements.

2. Prompt-driven Speaker Generation

2.1. System Overview

As shown in Figure 1, our methodology extends the text-to-speech (TTS) task by utilizing both content text and the prompt from listener impressions as inputs. The content text controls the linguistic aspects of the generated speech, while the prompt from listener impressions modulates the speaker's characteristics. We detail the process of prompt construction in section 3.1. Our approach begins with pre-training a Variational Inference with adversarial learning for end-to-end Text-to-Speech (VITS) system [14], which is modified in our experiment to condition

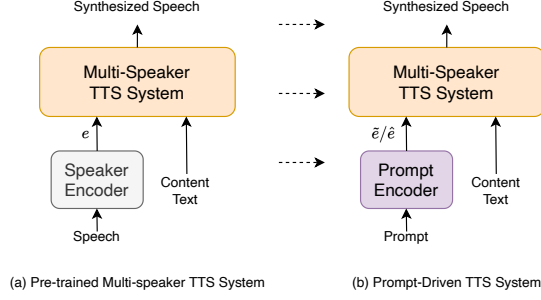


Figure 1: Overview of our system. \tilde{e} and \hat{e} are two types of outputs of the prompt encoder. Refer to Figure 2 for more details.

on speaker embeddings e derived from an external speaker encoder. Furthermore, we replaced the original speaker encoder with a prompt encoder. This modification necessitates that the prompt encoder is capable of accurately mapping prompts to their respective speaker embeddings, thereby enabling the precise control of speaker characteristics through textual prompts.

In the following sections, we introduce two methods to map the prompt text to speaker embedding, the discriminative method and the generative method. In the discriminative method, the speaker embedding is deterministically determined by the prompt, which is widely used in previous multi-modal linking models [11, 12, 13]. Besides, we also propose to use the generative flow-matching [15] model to learn the distribution of the speaker embeddings conditioned on the prompt.

2.2. Discriminative Method

In this section, we introduce a discriminative model to map the text prompt to speaker embedding. Unlike other multi-modal linking models, e.g. CLIP [11] and CLAP [12], we update only the text prompt encoder here, which enables our model to be easily adapted to any pre-trained multi-speaker text-to-speech system. As depicted in Figure 2(a), each text prompt is initially appended with a $[CLS]$ token. This modified prompt is then processed by RoBERTa [16]¹, for which the output at the $[CLS]$ token, denoted as o_{CLS} , encapsulates the comprehensive information of the text prompt. Finally, $o_{CLS} \in \mathbb{R}^d$ is fed into another projection module to obtain the predicted speaker embedding $\tilde{e} \in \mathbb{R}^d$. Considering that many speaker recognition systems optimize the speaker embedding in the hyper-sphere space [17, 18], we update the discriminative model by simultaneously minimizing the L2 distance and maximizing the cosine similarity between \tilde{e} and the ground truth embedding e . The loss function is formulated as follows:

$$\mathcal{L} = \|\tilde{e} - e\|^2 + (1 - \text{cosine_similarity}(\tilde{e}, e)) \quad (1)$$

We also explore using the LoRA [10] in Figure 2(a) module to enhance the RoBERTa for our task and we consider the RoBERTa without LoRA as our baseline in our experiment.

2.3. Generative Method based on Flow Matching

Although discriminative multi-modal linking methods have shown commendable performance in downstream tasks, e.g. prompt-driven speech generation [7], image generation [19] and

¹<https://huggingface.co/nlp-waseda/roberta-base-japanese-with-auto-jumanpp>

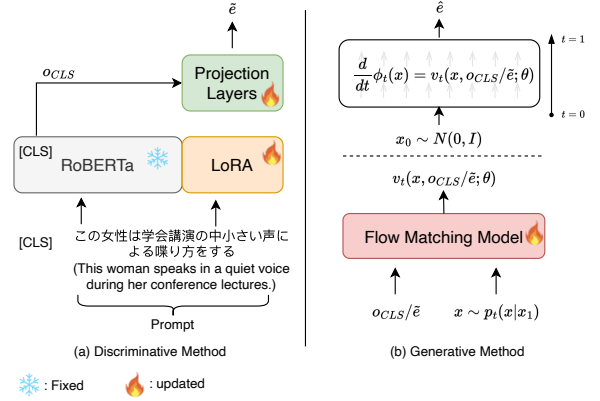


Figure 2: The Prompt Encoder Design.

audio generation [20], the relationship between text prompts and speaker embeddings is not strictly one-to-one. A single prompt can often describe different speakers, highlighting a complex one-to-many mapping challenge. To address this inherent complexity, we propose the adoption of a Flow Matching (FM) based generative model [15] for generating speaker embeddings from text prompts.

2.3.1. Flow Matching Algorithm

Modeling the distribution of data points $x_1 \in \mathbb{R}^d$ sampled from an unknown distribution $q(x_1)$ using deep learning techniques presents significant challenges. The generative model is always designed to learn the transformation from a simple prior distribution p_0 (e.g., a Gaussian distribution) to a target distribution $p_1 \approx q$. The flow matching algorithm [15] is proposed to construct a continuous flow $\phi_t : \mathbb{R}^d \rightarrow \mathbb{R}^d, t \in [0, 1]$ for transforming the prior distribution into the target distribution by regressing the vector field $u_t \in \mathbb{R}^d$. The relationship between the flow and vector field is formulated using an ordinary differential equation (ODE):

$$\frac{d}{dt}\phi_t(x) = u_t(\phi_t(x)) \quad (2)$$

Thus, if we can approximate u_t using a neural network, we can construct the flow path. However, given the absence of a closed-form expression for u_t , we cannot approximate it directly. Lipman et al. [15] propose utilizing a conditional vector field $u_t(x|x_1)$ to replace the original vector field u_t , leading to the Conditional Flow Matching (CFM) objective:

$$\mathcal{L}_{\text{CFM}}(\theta) = \mathbb{E}_{t, q(x_1), p_t(x|x_1)} \|v_t(x, \theta) - u_t(x|x_1)\|^2 \quad (3)$$

where $p_t(x|x_1)$ denotes the probability density function conditioned on x_1 at time t , and $v_t(x, \theta)$ is the neural network we used to approximate $u_t(x|x_1)$. The authors in [15] also prove that approximating $u_t(x|x_1)$ is equivalent to approximating u_t .

To define the path of the flow, we utilize the optimal transport (OT) path as described in [15], where $p_t(x|x_1) = \mathcal{N}(x|tx_1, (1 - (1 - \sigma_{\min})t)^2 I)$ and $u_t(x|x_1) = (x_1 - (1 - \sigma_{\min})x)/(1 - (1 - \sigma_{\min})t)$. Here, σ_{\min} is a scalar marginally above zero.

Table 1: *Spearman Rank Correlation Coefficient (SRCC) between MOS scores from reference and synthesized speech.*

Scenario	System	Speaker Attribute									Avg
		expressiveness	confidence	relaxation	voice_depth	age	energy	pitch	speed	clarity	
Seen	Discriminative (w/o LoRA)	<u>0.72</u>	0.53	0.48	<u>0.75</u>	<u>0.86</u>	<u>0.71</u>	<u>0.89</u>	<u>0.89</u>	0.23	0.67
	Discriminative (w/ LoRA)	<u>0.71</u>	<u>0.69</u>	0.65	<u>0.83</u>	<u>0.90</u>	<u>0.76</u>	<u>0.94</u>	<u>0.85</u>	0.37	0.74
	Flow-Matching (w/ LoRA)	<u>0.68</u>	<u>0.53</u>	0.66	<u>0.76</u>	<u>0.79</u>	0.50	<u>0.86</u>	0.38	0.22	0.60
	Discriminative + Flow-Matching	<u>0.74</u>	<u>0.71</u>	<u>0.75</u>	<u>0.87</u>	<u>0.96</u>	<u>0.72</u>	<u>0.90</u>	<u>0.68</u>	0.35	0.74
Unseen	Discriminative (w/o LoRA)	0.04	0.05	0.46	0.38	0.67	0.29	<u>0.73</u>	0.57	-0.37	0.31
	Discriminative (w/ LoRA)	0.54	0.38	0.49	0.48	<u>0.77</u>	0.25	<u>0.81</u>	0.36	0.41	0.50
	Flow-Matching (w/ LoRA)	-0.10	0.12	0.32	0.42	<u>0.82</u>	0.39	<u>0.74</u>	0.14	0.21	0.34
	Discriminative + Flow-Matching	0.36	0.08	0.49	0.35	<u>0.74</u>	0.34	<u>0.75</u>	0.37	0.20	0.41

underline: The statistical significance (p-value) is less than 0.001, indicating the MOS scores of synthetic speech are significantly correlated with the MOS scores of reference speech.

Table 2: *FAD score and Naturalness MOS results on the CSJ evaluation set.*

System	FAD Score	Naturalness MOS
ground-truth	-	4.06 ± 0.25
Discriminative (w/o LoRA)	11.217	3.15 ± 0.25
Discriminative (w/ LoRA)	5.244	3.45 ± 0.19
Flow-Matching (w/ LoRA)	3.559	3.52 ± 0.26
Discriminative + Flow-Matching	3.126	3.50 ± 0.24

speech from both objective and subjective perspectives. Results in Table 2 reveal the indispensable role of the LoRA module in enhancing speech synthesis, corroborating our hypothesis that merely augmenting the language model with additional layers is insufficient for this task. Furthermore, we demonstrate that our novel approach of generating speaker embeddings through the generative flow-matching model surpasses discriminative methods in terms of speech fidelity and naturalness. Notably, the combination of discriminative and generative techniques yields further improvement in the fidelity of synthesized speech.

4.2. Speaker information relevance between synthesized speech and prompt

In Section 3.3.2, we evaluate our systems in both seen and unseen speaker scenarios by collecting 20 Mean Opinion Score (MOS) ratings (corresponds to 20 speakers) for each system regarding a specific speaker attribute. We calculate the Spearman Rank Correlation Coefficient (SRCC) [29] between the MOS scores from synthesized speech and reference speech and list the results in Table 1.

Results from the seen scenario indicate that, aside from the clarity attribute, our systems effectively capture the speaker’s characteristics, with discriminative methods outperforming generative ones in terms of SRCC values. Despite this, as section 4.1 discusses, generative systems excel in creating high-fidelity audio. A synergistic approach, integrating both discriminative and generative techniques, achieves an optimal balance in preserving speaker characteristics and improving synthesized audio fidelity and naturalness. It should be noted that, apart from the pitch and speech attributes, which can be manipulated by signal processing strategy, our systems also capture the voice depth and age information from prompts very well. Manipulating these abstract concepts in speech is precisely the greatest strength of prompt-driven TTS systems. Besides, we also plot the MOS scores from synthesized and reference speech and visualize the linear correlation between them in Figure 4. The visualization further demonstrates that our system can capture the specific speaker characteristics from prompts.

Results from the bottom part of Table 1 show that, for the

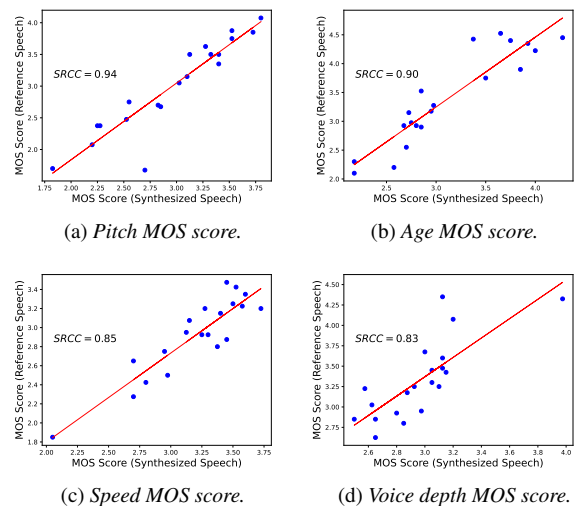


Figure 4: *MOS score linear correlation visualization between synthesized speech and reference speech. The Discriminative (w/ LoRA) system is used to generate speech for seen speaker scenario.*

unseen speaker scenario, the system’s ability to capture speaker characteristics in the prompt has weakened. This is because the prompt data amount in CSJ is still limited. In the future, we plan to train MOS predictors for speaker traits and use estimated MOS values for generating speaker impression prompts automatically for large amounts of speech data.

5. Conclusion

In this paper, we proposed to use prompts to specify and control the acoustic characteristics of the synthesized speech from a multi-speaker text-to-speech system. Different from previous works, listener impression scores are used to construct the prompts, thereby saving human resources and make the prompts closer to everyday expressions. Furthermore, we integrated a lightweight adapter module, LoRA, to efficiently fine-tune pre-trained language models for our specific requirements, yielding significant enhancements. Besides, we also decoupled the prompt-to-speaker module and the TTS system, which makes the whole system more flexible. To generate speaker embeddings from the prompt, we explored the discriminative method and flow-matching based generative method. Interestingly, We found that these two methods each have their own advantages, and combining them can further enhance the model.

6. Acknowledgements

This work was conducted during the first author’s internship at NII, Japan. This study was partially supported by Google AI for Japan program. This work was partially supported in part by China NSFC projects under Grants 62122050 and 62071288, in part by Shanghai Municipal Science and Technology Commission Project under Grant 2021SHZDZX0102.

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